

(AUTONOMOUS) Accredited by National Board of Accreditation, AICTE, New Delhi, Accredited by NAAC with "A" Grade – 3.32 CGPA, Recognized under 2(f) & 12(B) of UGC Act 1956, Approved by AICTE, New Delhi, Permanent Affiliation to JNTUK, Kakinada Seetharampuram, W.G.DT., Narsapur-534280, (Andhra Pradesh)

DEPARTMENT OFELECTRONICS AND COMMUNICATION ENGINEERING

TEACHING PLAN

Course Code	CourseTitle	Seme	ster	Branches	Contact Periods /Weck	Acade Yea	mic r co	Date of mmencement of Semester	
20EC3T 03	Signals & Systems	11	I	ECE	6	2021-2	022	25-10-2021	
COURS After co	SE OUTCOMES mpletion of the course	studen	ts are a	able to					
1	Describe the signal fundamentals in terms of types and how to represent various signals(K1)								
2	Explain the concept of Fourier series and Fourier transforms to determine the signal and system characteristics. (K2, K4)								
3	Demonstrate the concept of sampling theorem, convolution and correlation and also signal transmission through linear systems. (K3)								
4	Demonstrate the concept of ROC (Region Of Convergence) using Laplace and Z- Transforms to analyze the continuous and discrete time systems. (K3, K4)								
UNIT	Out Comes / Bloom's Level	Topics No.		Topics/Activit	y I	Text Book / Reference	Contact Hour	Delivery Method	
		τ	JNIT-1	: INTRODUC	CTION TO	SIGNAI	LS AND	SYSTEMS	
	CO1: Describe the	1.1	Intro Signa signa signa Aper	oduction to als:Continuous ls and Discrete ls, Periodic and iodic signals	time time 1	T1, T2	1		
	signal fundamentals in terms of types	1.2	Even Ener	and Odd signa gy and Power s	ls, ignals	T1, T2	1	Chalk & Talk,	
I	and how to represent the various signals.	1.3	Deter signation and S	rministic and R Ils-Complex Ex Sinusoidal signa	andom ponential als	T1, T2	1	Smart Board and PPT	
	(K1)	1.4	Stand impu ramp	dard Functions llse and Unit sto signal	- Unit ep-Unit	T1, T2	1		
		1.5	Intro Cont Line	oduction to System inuous time system ar and Non- Lin	stems: stems- near	T1, T2	1		



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			1.6	Discrete time systems- Linear and Non-Linear	т1 т2	1	
			1.7	Time Invariant and Time	11, 12	1	
				Variant systems	T1, T2	-	
			1.8	Causal and Non-causal system- BIBO system- Systems with and without	T1, T2	2	
			10	memory Broblems	T1 T2	2	
			1.9	FIODEIIIS	11, 12	12	
				Fotal		12	
				UNIT-2: CONVOLUTIO	ON, COR	RELATI	ON
9	1		2.1	Convolution and Correlation	T1	1	
			2.2	Graphical representation of	T1	1	
				convolution,			
			2.3	,Properties of Convolution	T1		
		CO3: Demonstrate		like Cumulative, Associative,		1	
		the concept of	24	Shifting Scaling	T1	1	Chalk & Talk,
		sampling theorem,	2.5	Convolution Integral and	T1		Smart Board
		convolution and	2.0	Convolution Sum		1	and
	П	correlation and also	2.6	Cross correlation	T1	1	PP1
		signal transmission	2.7	Auto correlation of functions,	T1	1	
		through linear	2.8	Properties of correlation	T1	1	
		Systems. (K3)		function with examples		1	
			2.9	Relation between Auto	T1	1	
			0.10	correlation and energy signal,	T1	1	
		Columnities and an and a second	2.10	PSD.		1	
			2.11	Problems	11	12	
				IOTAI INIT 2. FOUDIED SED	IFS AND) SAMPI	ING
				UNII-5; FOUNIER SER			
		CO2:Explain the	3.1	Concept pf Orthogonal	T1	1	
		concept of Fourier		functions with examples		1	
		series and Fourier	3.2	Introduction to Fourier Series	<u>T1</u>	1	Chalk & Talk,
	ш	transforms to	3.3	Representation of	T1		Smart Board
		determine the		Continuous-Time Periodic		I	and
		signal and system	21	Deriving Fourier transform	T1		PPT
		K_A	5.4	coefficients	11	1	
	and the second se	M +)		0001110101113		•	
			3.5	Relation between		1	



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			Trigonometric coefficients anf Exponential coefficient.	T1		
		3.6	Dirchillet conditions	T1	1	
		3.7	Sampling Theorem	T1	1	
		3.8	Time domain and	T1		
			frequency domain statements-			
		3.9	Reconstruction of a	T1	1	
			Signal from its sample-			
		3.10	The Effect of under	T1		
			sampling (Aliasing).		1	
		3.12	Problems	T1	1	
				Total	12	
		UNI	Γ - 4 CONTINUOUS-TIME TR	ANSFOI	RMS	
		41	Introduction to Laplace			
			Transform.	Т1 Т 2	1	
		10		11, 12		-
	CO4: Demonstrate	4.2	Unilateral and bi-lateral	T 1 T 0	1	
	the concept of ROC			11, 12		-
	(Region Of	4.3	ROC, Constraints of ROC,	T1, T2	1	
	Convergence) using	4.4	Laplace Transform of		1	
	Laplace and		standard functions,	T1, T2	1	
	2- Iransforms to	4.5	Properties of transforms	T1, T2	1	1
	continuous and	4.6	Inverse Laplace Transform.	T1, T2	1	Chalk & Talk,
IV	discrete time	4.7	Initial and Final Value			Smart Board
	systems. (K3, K4)		theorems	T1, T2		and
		4.8	Fourier Transform:	T1, T2	1	РРТ
		4.9	Unilateral and bi-lateral	T1	-	-
	CO2: Explain the		Fourier Transform		1	
	concept of Fourier	4.10	Properties of Fourier	T1		-
	series and Fourier		transform,		I	
	dotormine to	4.11	The Convolution Property,	T1	1	1
	signal and system		Parseval's Theorem,		I	
	characteristics (K2)	4.12	The Multiplication Property.	T1	1	
	K4)	4.13	Problems on Inverse Fourier	T1	1	
			Transform		I	
		4.14	Relation between LT & CTFT	T1	1	



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		UNI	Г – 5: DISCRETE-TIME TRA	NSFORM	AS	
	CO4: Demonstrate	5.1	Unilateral and bi-lateral z- transform.	T2	1	
		5.2	ROC, Constraints of ROC,	T2	1	
	the concept of ROC	5.3	Properties of Z-transforms,	T2	1	Chalk & Talk, Smart Board
	(Region Of Convergence) using Laplace and Z- Transforms to applyze the	5.4	Convolution Property,	T2	1	
v		5.5	Z-Transform(T2	1	
		5.6	Direct and Indirect methods	T2	1	and PPT
	continuous and discrete time systems. (K3, K4)	5.7	Initial and Final Value theorems,.	T2	1	
		58	Relation between DTFT and Z-Transform	T2	1	
Content		5.14	Applications of signals and sampling in communication.	T2	1	
Syllabus (if needed)		5.15	Filter design using Transform techniques.	T2	1	
				Total	15	
		CI	IMULATIVE PROPOSED PE	RIODS	65	

CUMULATIVE PROPOSED PERIODS

Text Books:

S.No.	AUTHORS, BOOK TITLE, EDITION, PUBLISHER, YEAR OF PUBLICATION								
1.	B.P. Lathi, "Principles of Linear Systems & Signals", Oxford Press, Second								
	Edition2005.(UNITS -I,II&III)								
2.	A.V.Oppenheim, A.S.Willsky and S.H.Nawab,, Signals and Systems - 4nd Edition, Prentice-								
	Hall India.2009 (UNITS –IV&V)								

Reference Books:

S.No.	AUTHORS, BOOK TITLE, EDITION, PUBLISHER, YEAR OF PUBLICATION								
1.	John G. Proakis and Manolakis, "Digital Signal Processing, Principles, Algorithms and								
	Applications", PearsonEducation, 3rdedition, 2002								
2.	1. Simon Haykin and Barry Van Veen, "Signals and Systems", John Wiley & Sons In, 2001.								



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3.	https://www.tutofiaispoint.com/signass_ana_s/storing/signass_ana_				
4.	www.booksboon.com				
5.	www.manybooks.com				
6	https://ocw.mit.edu/resources/res-6-00/-signals-and-systems-spring-2011				
υ.	https://oew.mineda.rese				

		Name	Signature with Date
i.	Faculty I	Dr. B.S.Rao	Burlin
ii.	Faculty II (for common Course)	Mr.J.E.N.Abhilash	JEN AChlah
iii.	Course Coordinator	Dr. B.S.Rao	Burlind
iv.	Module Coordinator	Dr. N. Kopperen Devi	Natopan dew
v.	Programme Coordinator	Dr.B.S.Rao	Burtul

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